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THE DISTRIBUTION OF RANDOM EVOLUTION IN ERLANG SEMI-MARKOV MEDIA

We study a one-dimensional random motion by using a general Erlang distribution for the sojourn times of a switching process and obtain the solution of a four-order hyperbolic PDE in the 2-Erlang case.

1. INTRODUCTION

In paper [1], we studied a one-dimensional random motion with the m -Erlang distribution between consequent epochs of velocity alternations. Let $f(t, x)$ be the probability density function (pdf) of a particle position at time t , provided that it exists. We obtained the following higher order hyperbolic equations for $f(t, x)$:

$$(1) \quad \left(\frac{\partial}{\partial t} - v \frac{\partial}{\partial x} + \lambda \right)^m \left(\frac{\partial}{\partial t} + v \frac{\partial}{\partial x} + \lambda \right)^m f(t, x) - \lambda^{2m} f(t, x) = 0,$$

where $v > 0$ is the velocity of a particle, and λ is the parameter of the m -Erlang distribution. It is assumed that the particle started at $x = 0$, and, hence, $f(0, x) = \delta(x)$.

The pdf $f(t, x)$ can be represented in the form $f(t, x) = f_c(t, x) + f_s(t, x)$, where $f_c(t, x)$ is the absolute continuous part, and $f_s(t, x)$ is the singular part w.r.t. Lebesgue measure on the line.

Lemma 1.1. *The singular part $f_s(t, x)$ of the pdf $f(t, x)$ is of the following form:*

$$(2) \quad f_s(t, x/v) = \delta(t - x/v) e^{-\lambda t} \sum_{i=0}^{m-1} (\lambda t)^i / i!.$$

Proof. It is evident that, for $t = x/v$, the pdf $f(t, x)$ has the singularity given by Eq. (2). Let us show that, for $t > |x/v|$, the pdf $f(t, x)$ has no singularity w.r.t. Lebesgue measure on \mathbb{R} . By v_k , we denote the random event " k velocity alternations occurred". For $\Delta x = [x, x + \Delta]$, $\Delta > 0$, let us consider

$$P_{v_0}(x(t) \in \Delta x) = \sum_{k \geq 1} P(x(t) \in \Delta x, \nu_k),$$

which is the probability of the event where at least one alternation occurred and $x(t) \in \Delta x$. Let us show that, for each $t > 0$, there exists a constant $C_t < \infty$ such that

$$\sup_x \frac{P_{v_0}(x(t) \in \Delta x)}{\Delta x} < C_t.$$

By $\theta_k, k \geq 1$, we denote the time between $(k - 1)$ -th and k -th velocity alternations. Recall that $\theta_k, k \geq 1$, are independent m -Erlang distributed random variables. It is easy to verify that

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$$\begin{aligned}
P_{\bar{v}_0}(x(t) \in \Delta x) &= \sum_{k \geq 1} P \left(\sum_{i=1}^k (-1)^{i+1} \theta_i v + (-1)^k \left(t - \sum_{i=1}^k \theta_i v \right) \in \Delta x, \sum_{i=1}^k \theta_i < t \right) \\
&= \sum_{k \geq 1} P \left(\left(\sum_{i=1}^k (-1)^{i+1} \theta_i - (-1)^k \sum_{i=1}^k \theta_i \right) v \in \Delta x - (-1)^k vt, \sum_{i=1}^k \theta_i < t \right) \\
&= \sum_{l \geq 0} P \left(2v(\theta_1 + \theta_3 + \dots + \theta_{2l+1}) \in \Delta x - vt, \sum_{i=1}^{2l+1} \theta_i < t \right) \\
&= \sum_{l \geq 0} P \left(-2v(\theta_2 + \theta_4 + \dots + \theta_{2l+2}) \in \Delta x + vt, \sum_{i=1}^{2l+2} \theta_i < t \right) \\
&\leq \sup_x \sum_{l \geq 0} P \left(2v \sum_{i=1}^l \theta_{2i-1} \in \Delta x, 2v \sum_{i=1}^l \theta_{2i} < vt - x \right) \\
&\quad + \sup_x \sum_{l \geq 0} P \left(-2v \sum_{i=1}^l \theta_{2i} \in \Delta x, 2v \sum_{i=1}^l \theta_{2i+1} < vt + x \right).
\end{aligned}$$

Since $|x| \leq vt$ and, for every $m \geq 1$, the pdf $p_m(x, \lambda)$ of the m -Erlang distribution with the parameter λ satisfies $p_m(x, \lambda) \leq \lambda$, we have

$$\begin{aligned}
&\sum_{l \geq 1} P(2v(\theta_1 + \theta_3 + \dots + \theta_{2l-1}) \in \Delta x, 2v(\theta_2 + \theta_4 + \dots + \theta_{2l}) < vt - x) \\
(3) \quad &\leq \frac{\lambda \Delta}{2v} \sum_{l \geq 1} P(\theta_2 + \theta_4 + \dots + \theta_{2l} < t).
\end{aligned}$$

Since θ_i is m -Erlang distributed, we have, for $2lm + 1 > t$,

$$P(\theta_2 + \theta_4 + \dots + \theta_{2l} < t) \leq \left(e^{\lambda t} - \sum_{i=0}^{2lm} \frac{(\lambda t)^i}{i!} \right) e^{-\lambda t} \leq \frac{(\lambda t)^{2lm+1} e^{-\lambda t}}{2lm!(2lm+1-\lambda t)}.$$

Therefore, taking (3) into account, there exists a constant A_t such that

$$\sup_x \sum_{l \geq 1} P \left(2v \sum_{i=1}^l \theta_{2i-1} \in \Delta x, 2v \sum_{i=1}^l \theta_{2i} < vt - x \right) \leq A_t \Delta.$$

In the same way, we can show that there exists a constant B_t such that

$$\sup_x \sum_{l \geq 1} P \left(-2v \sum_{i=1}^l \theta_{2i} \in \Delta x, 2v \sum_{i=1}^l \theta_{2i+1} < vt + x \right) \leq B_t \Delta.$$

Putting $C_t = A_t + B_t$, we conclude the proof.

Corollary 1.1. *The absolute continuous part $f_c(t, x)$ of the pdf $f(t, x)$ satisfies Eq. (1) for $t < |\frac{x}{v}|$.*

We now study the behavior of the continuous part $f_c(t, x)$ close to lines $t = \pm \frac{x}{v}$.

Lemma 1.2. *For $m \geq 2$, we have*

$$\begin{aligned}
\lim_{\varepsilon \downarrow 0} \frac{P\{0 < t - x(t) < \varepsilon\}}{\varepsilon} &= \frac{\lambda^m t^{m-1} e^{-\lambda t}}{2(m-1)!}, \\
\lim_{\varepsilon \rightarrow 0} \frac{P\{t + x(t) < \varepsilon\}}{\varepsilon} &= 0.
\end{aligned}$$

Proof. It is easy to verify that

$$P\{0 < t - x(t) \leq \varepsilon\} = P\left\{t - \frac{\varepsilon}{2} \leq \theta_1 < t\right\} + \int_0^t P\left\{\theta_3 \geq t - u, \theta_2 \leq \frac{\varepsilon}{2}, \theta_1 \in du\right\} + o(\varepsilon),$$

where $\theta_i, i = 1, 2, 3$ are independent m -Erlang distributed random variables with the parameter λ . Since $\int_0^t P(\theta_3 \geq t - u, \theta_2 \leq \frac{\varepsilon}{2}, \theta_1 \in du) = o(\varepsilon)$, we pass to the limit and obtain

$$\begin{aligned} \lim_{\varepsilon \downarrow 0} \frac{P\{0 < t - x(t) < \varepsilon\}}{\varepsilon} &= \lim_{\varepsilon \downarrow 0} \frac{e^{-\lambda t}}{\varepsilon} \left(\left(\sum_{i=0}^{m-1} \frac{(\lambda t)^i}{i!} \right) - e^{\lambda \frac{\varepsilon}{2}} \left(\sum_{i=0}^{m-1} \frac{(\lambda (t - \frac{\varepsilon}{2}))^i}{i!} \right) \right) \\ &= \frac{\lambda^m t^{m-1} e^{-\lambda t}}{2(m-1)!}. \end{aligned}$$

Similarly, $P\{t + x(t) \leq \varepsilon\} = P\{\theta_2 \geq t - \frac{\varepsilon}{2}, \theta_1 \leq \frac{\varepsilon}{2}\} + o(\varepsilon)$, and it is easily seen that

$$\lim_{\varepsilon \downarrow 0} \frac{P\{t + x(t) < \varepsilon\}}{\varepsilon} = 0.$$

Remark 1.1. The case where $m = 1$ will be considered in what follows as an example.

Remark 1.2. We will seek solutions of Eq. (1) among functions whose continuous part $f_c(t, x)$ satisfies the conditions

$$(4) \quad \lim_{x \uparrow t} f_c(t, x) = \lim_{\varepsilon \downarrow 0} \frac{P\{0 < t - x(t) < \varepsilon\}}{\varepsilon}, \quad \lim_{x \downarrow -t} f_c(t, x) = \lim_{\varepsilon \downarrow 0} \frac{P\{t + x(t) < \varepsilon\}}{\varepsilon}.$$

By applying the transformation $f(t, x) = e^{\lambda t} g(t, x)$ and changing the variable $y = \frac{x}{v}$, we reduce Eq. (1) to

$$(5) \quad \left(\frac{\partial^2}{\partial t^2} - \frac{\partial^2}{\partial y^2} \right)^m g_c(t, y) - \lambda^{2m} g_c(t, y) = 0$$

with the singular part $g_s(t, y) = \left(\sum_{i=0}^{m-1} \frac{(\lambda t)^i}{i!} \right) \delta(t - y)$.

In the sequel, we assume, without loss of generality, that $\lambda = 1$. By introducing the function $\mathbf{f}(t, y, z) = e^z g_c(t, y)$, we reduce Eq. (5) to the equation

$$(6) \quad \left(\frac{\partial^2}{\partial t^2} - \frac{\partial^2}{\partial y^2} \right)^m \mathbf{f}(t, y, z) - \frac{\partial^{2m}}{\partial z^{2m}} \mathbf{f}(t, y, z) = 0.$$

We will seek solutions of this equation by using the theory of differentiable functions on commutative algebras [2].

2. MAIN RESULTS

Let A_0 be a $2m$ -dimensional commutative algebra over \mathbb{R} . We assume that the set $e_0, e_1, \dots, e_{2m-1}$ is a basis of A_0 with the Cayley table:

$$e_i e_j = e_{i \oplus j},$$

where $i \oplus j = i + j \pmod{2m}$.

The algebra A_0 has a matrix representation

$$e_k \rightarrow P_k = P_1^k,$$

where $P_1 = [p_{ij}]_{2m \times 2m}$, $p_{ii+1} = 1$ for $0 \leq i \leq 2m-1$, $p_{2m0} = 1$, and $p_{ij} = 0$ for the rest of i, j .

We put

$$\tau_0^l = e_l, \quad l = 0, 1, \dots, 2m-1,$$

$$\begin{aligned}\tau_1^l &= e_l i \sin s, \quad l = 0, 1, \dots, 2m-1, \\ \tau_2^l &= e_l \cos s, \quad l = 0, 1, \dots, 2m-1, \\ \tau_{2k}^l &= e_l \cos ks, \quad \tau_{2k+1}^l = e_l i \sin(k+1)s, \quad l = 0, 1, \dots, 2m-1, \\ & \quad k = 0, 1, 2, \dots\end{aligned}$$

It is easily seen that $\tau_{2n}^0 \tau_{2k}^0 = \frac{1}{2} \left(\tau_{2(n-k)}^0 + \tau_{2(n+k)}^0 \right)$, $n \geq k$,

$$\tau_{2n+1}^{l_1} \tau_{2k+1}^{l_2} = \frac{1}{2} \left(\tau_{2(n-k)}^{l_1 \oplus l_2} - \tau_{2(n+k)}^{l_1 \oplus l_2} \right), \quad n \geq k,$$

$$\tau_{2n+1}^{l_1} \tau_{2k}^{l_2} = \frac{1}{2} \left(\tau_{2(n-k)+1}^{l_1 \oplus l_2} + \tau_{2(n+k)+1}^{l_1 \oplus l_2} \right), \quad n \geq k.$$

We now introduce the algebra

$$A = \left\{ \sum_{k=0}^{+\infty} \sum_{l=0}^{2m-1} (a_{2k}^l \tau_{2k}^l + a_{2k+1}^l \tau_{2k+1}^l) \mid a_j^l \in \mathbb{R} \right\},$$

where $\sum_{k=0}^{+\infty} \sum_{l=0}^{2m-1} (|a_{2k}^l|^2 + |a_{2k+1}^l|^2) < +\infty$.

It is easy to verify that A is commutative.

We consider the subspace $B = \{a_0 \tau_1^1 + a_1 \tau_2^1 + a_2 \tau_0^0 \mid a_i \in \mathbb{R}\}$ of the algebra A .

Let us introduce the function $\mathbf{f} : B \rightarrow A$ ($\mathbf{f}(t, y, z) = f(e_1(tc \cos s + y i \sin s) + z)$) as follows:

$$\mathbf{f}(t, y, z) = \sum_{k=0}^{+\infty} \sum_{l=0}^{2m-1} (v_{2k}^l(t, y, z) \tau_{2k}^l + v_{2k+1}^l(t, y, z) \tau_{2k+1}^l).$$

The function \mathbf{f} is called B/A differentiable at $\mathbf{x}_0 \in B$ if there exists $\mathbf{f}'(\mathbf{x}_0) \in A$ such that, for any $\mathbf{h} \in B$,

$$\mathbf{f}'(\mathbf{x}_0) \mathbf{h} = \lim_{\varepsilon \rightarrow 0} \frac{\mathbf{f}(\mathbf{x}_0 + \varepsilon \mathbf{h}) - \mathbf{f}(\mathbf{x}_0)}{\varepsilon}$$

In [2], it was proved that if \mathbf{f} is B/A differentiable, then

$$(7) \quad \frac{\partial}{\partial t} \mathbf{f} = e_1 \cos s \frac{\partial}{\partial z} \mathbf{f}$$

and

$$(8) \quad \frac{\partial}{\partial y} \mathbf{f} = e_1 i \sin s \frac{\partial}{\partial z} \mathbf{f}.$$

In this case, all $v_{2k}^l(t, y, z)$ are solutions of Eq. (6). Indeed,

$$\left(\frac{\partial^2}{\partial t^2} - \frac{\partial^2}{\partial y^2} \right)^m \mathbf{f} - \frac{\partial^{2m}}{\partial z^{2m}} \mathbf{f} = e_1^{2m} (\cos^2 s - (i \sin s)^2)^m - 1 = 0.$$

In the sequel, we denote the element e_1 by \mathbf{e} .

We will seek a solution of Eq. (5) in the form

$$g_c(\mathbf{e}(t \cos s + y i \sin s)) = e^{\mathbf{e}(t \cos s + y i \sin s)}$$

. Since $f(\mathbf{e}(t \cos s + y i \sin s) + z) = g_c(\mathbf{e}(t \cos s + y i \sin s)) e^z$, we have

$$v_k^l(t, y, z) = u_k^l(t, y) e^z, \quad l = 0, 1, \dots, 2m-1, \quad k = 0, 1, 2, \dots,$$

where $g_c(t, y) = \sum_{k=0}^{+\infty} \sum_{l=0}^{2m-1} (u_{2k}^l(t, y) \tau_{2k}^l + u_{2k+1}^l(t, y) \tau_{2k+1}^l)$.

Therefore, we obtain the functions $u_0^l(t, y)$ for $t \geq |y|$ from the equation

$$\begin{aligned}& \sum_{l=0}^{2m-1} u_0^l(t, y) \tau_0^l = \sum_{l=0}^{2m-1} u_0^l(t, y) \mathbf{e}^l \\ &= \frac{1}{2\pi} \int_{-\pi}^{\pi} e^{\mathbf{e}(t \cos s + y i \sin s)} ds = J_0 \left(\mathbf{e} i \sqrt{y^2 - t^2} \right) = I_0 \left(\mathbf{e} \sqrt{t^2 - y^2} \right),\end{aligned}$$

where I_k (resp. J_k) is the modified Bessel (resp. Bessel) function of the first kind and k -th order [4].

Equations (7) and (8) yield the following Cauchy–Riemann-type conditions:

$$(9) \quad \begin{aligned} \frac{\partial}{\partial t} u_0^{l \oplus 1} &= \frac{1}{2} u_2^l, \\ \frac{\partial}{\partial t} u_1^{l \oplus 1} &= \frac{1}{2} u_3^l, \\ \frac{\partial}{\partial t} u_2^{l \oplus 1} &= u_0^l + \frac{1}{2} u_4^l, \\ \frac{\partial}{\partial t} u_{2k-1}^{l \oplus 1} &= \frac{1}{2} (u_{2k-3}^l + u_{2k+1}^l), \\ \frac{\partial u_{2k}^{l \oplus 1}}{\partial t} &= \frac{1}{2} (u_{2(k-1)}^l + u_{2(k+1)}^l), \\ k &= 2, 3, \dots; \end{aligned}$$

and

$$(10) \quad \begin{aligned} \frac{\partial}{\partial y} u_0^{l \oplus 1} &= -\frac{1}{2} u_1^l, \\ \frac{\partial u_1^{l \oplus 1}}{\partial y} &= u_0^l - \frac{1}{2} u_4^l, \\ \frac{\partial}{\partial y} u_2^{l \oplus 1} &= -\frac{1}{2} u_3^l, \\ \frac{\partial u_{2k+1}^{l \oplus 1}}{\partial y} &= \frac{1}{2} (u_{2k}^l - u_{2(k+2)}^l), \\ \frac{\partial u_{2k+2}^{l \oplus 1}}{\partial y} &= \frac{1}{2} (u_{2k-1}^l - u_{2k+3}^l), \\ k &= 1, 2, \dots \end{aligned}$$

By using Eqs. (9) and (10) and the functions $u_0^l(t, y)$, we can obtain recurrently the function $u_k^l(t, y)$ for any $k \geq 1$, which will be used to solve Eq. (1).

In the sequel, unless otherwise specified, the case where $m = 2$ is studied. In this case, $f_s(t, y)$ is of the form $f_s(t, x) = e^{-t} (1+t) \delta(t-x)$, and, hence,

$$g_s(t, y) = (1+t) \delta(t-y).$$

The algebra A_0 is as follows:

$$A_0 = \{a + e_1 b + e_2 c + e_3 d \mid a, b, c, d \in \mathbb{R}\}.$$

Here, the basis $e_l = \mathbf{e}^l$, $l = 0, 1, 2, 3$, and \mathbf{e} has the matrix representation

$$\mathbf{e} \rightarrow P = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{bmatrix}.$$

Therefore, we have $\tau_0^0 = 1$, $\tau_{2k}^0 = \cos ks$, $\tau_{2k}^l = \mathbf{e}^l \cos ks$, $\tau_{2k+1}^l = \mathbf{e}^l \sin(k+1)s$, $l = 0, 1, 2, 3$, $k = 0, 1, 2, \dots$

Taking into account that $g_c(\mathbf{e}(t \cos s + y \sin s)) = e^{\mathbf{e}(t \cos s + y \sin s)}$, we have

$$\begin{aligned} u_0^0(t, y) + \mathbf{e} u_0^1(t, y) + \mathbf{e}^2 u_0^2(t, y) + \mathbf{e}^3 u_0^3(t, y) &= \frac{1}{2\pi} \int_{-\pi}^{\pi} e^{\mathbf{e}(t \cos s + y \sin s)} ds \\ &= I_0(\mathbf{e} \sqrt{t^2 - y^2}). \end{aligned}$$

It is easily seen that

$$\begin{aligned} I_0\left(e\sqrt{t^2-y^2}\right) &= \frac{I_0\left(\sqrt{t^2-y^2}\right)+I_0\left(i\sqrt{t^2-y^2}\right)}{2}+e^2\left(\frac{I_0\left(\sqrt{t^2-y^2}\right)-I_0\left(i\sqrt{t^2-y^2}\right)}{2}\right) \\ &= \frac{I_0\left(\sqrt{t^2-y^2}\right)+J_0\left(\sqrt{t^2-y^2}\right)}{2}+e^2\frac{I_0\left(\sqrt{t^2-y^2}\right)-J_0\left(\sqrt{t^2-y^2}\right)}{2}. \end{aligned}$$

Therefore, for $t \geq |y|$, we have $u_0^1(t, y) = u_0^3(t, y) = 0$ and

$$\begin{aligned} u_0^0(t, y) &= \frac{I_0\left(\sqrt{t^2-y^2}\right)+J_0\left(\sqrt{t^2-y^2}\right)}{2}, \\ u_0^2(t, y) &= \frac{I_0\left(\sqrt{t^2-y^2}\right)-J_0\left(\sqrt{t^2-y^2}\right)}{2}. \end{aligned}$$

It follows from the first two equations of (10) that

$$\begin{aligned} u_1^1 &= -2\frac{\partial}{\partial y}u_0^2 = -\frac{\partial\left[I_0\left(\sqrt{t^2-y^2}\right)-J_0\left(\sqrt{t^2-y^2}\right)\right]}{\partial y} \\ &= \frac{y}{\sqrt{t^2-y^2}}\left(I_1\left(\sqrt{t^2-y^2}\right)+J_1\left(\sqrt{t^2-y^2}\right)\right), \\ u_1^3 &= -2\frac{\partial}{\partial y}u_0^0 = -\frac{\partial\left[I_0\left(\sqrt{t^2-y^2}\right)+J_0\left(\sqrt{t^2-y^2}\right)\right]}{\partial y} \\ &= \frac{y}{\sqrt{t^2-y^2}}\left(I_1\left(\sqrt{t^2-y^2}\right)-J_1\left(\sqrt{t^2-y^2}\right)\right), \\ u_1^0 &= -2\frac{\partial}{\partial y}u_0^1 = 0, \\ u_1^2 &= -2\frac{\partial}{\partial y}u_0^3 = 0. \end{aligned}$$

Then the Cauchy–Riemann-type conditions (9) yield

$$\begin{aligned} u_2^0(t, y) &= 2\frac{\partial u_0^1(t, y)}{\partial t} = 0; \\ u_2^1(t, y) &= 2\frac{\partial u_0^2(t, y)}{\partial t} = \frac{\partial\left(I_0\left(\sqrt{t^2-y^2}\right)-J_0\left(\sqrt{t^2-y^2}\right)\right)}{\partial t} \\ &= \frac{t}{\sqrt{t^2-y^2}}\left(I_1\left(\sqrt{t^2-y^2}\right)+J_1\left(\sqrt{t^2-y^2}\right)\right); \\ u_2^2(t, y) &= 2\frac{\partial u_0^3(t, y)}{\partial y} = 0; \\ u_2^3(t, y) &= 2\frac{\partial u_0^0(t, y)}{\partial t} = \frac{\partial\left[I_0\left(\sqrt{t^2-y^2}\right)+J_0\left(\sqrt{t^2-y^2}\right)\right]}{\partial t} \\ &= \frac{t}{\sqrt{t^2-y^2}}\left(I_1\left(\sqrt{t^2-y^2}\right)-J_1\left(\sqrt{t^2-y^2}\right)\right). \end{aligned}$$

Similarly, for u_3^l , we have

$$\begin{aligned}
u_3^0 &= 2 \frac{\partial}{\partial t} u_1^1 = 2 \frac{\partial}{\partial t} \left[\frac{y}{\sqrt{t^2 - y^2}} \left(I_1 \left(\sqrt{t^2 - y^2} \right) + J_1 \left(\sqrt{t^2 - y^2} \right) \right) \right] \\
&= - \frac{2ty}{\sqrt{(t^2 - y^2)^3}} \left(I_1 \left(\sqrt{t^2 - y^2} \right) + J_1 \left(\sqrt{t^2 - y^2} \right) \right) \\
&\quad + \frac{ty}{t^2 - y^2} \left(I_0 \left(\sqrt{t^2 - y^2} \right) + I_2 \left(\sqrt{t^2 - y^2} \right) + J_0 \left(\sqrt{t^2 - y^2} \right) - J_2 \left(\sqrt{t^2 - y^2} \right) \right); \\
u_3^2 &= 2 \frac{\partial}{\partial t} u_1^3 = 2 \frac{\partial}{\partial t} \left[\frac{y}{\sqrt{t^2 - y^2}} \left(I_1 \left(\sqrt{t^2 - y^2} \right) - J_1 \left(\sqrt{t^2 - y^2} \right) \right) \right] \\
&= - \frac{2ty}{\sqrt{(t^2 - y^2)^3}} \left(I_1 \left(\sqrt{t^2 - y^2} \right) - J_1 \left(\sqrt{t^2 - y^2} \right) \right) \\
&\quad + \frac{2ty}{t^2 - y^2} \left(I_0 \left(\sqrt{t^2 - y^2} \right) + I_2 \left(\sqrt{t^2 - y^2} \right) - J_0 \left(\sqrt{t^2 - y^2} \right) + J_2 \left(\sqrt{t^2 - y^2} \right) \right).
\end{aligned}$$

It is easily seen that $u_3^1 = u_3^3 = 0$.

Next, it follows from (9) that

$$\begin{aligned}
u_4^0 &= 2 \frac{\partial u_2^1}{\partial t} - 2u_0^0 = 2 \frac{\partial}{\partial t} \frac{t}{\sqrt{t^2 - y^2}} \left(I_1 \left(\sqrt{t^2 - y^2} \right) + J_1 \left(\sqrt{t^2 - y^2} \right) \right) - 2u_0^0 \\
&= \frac{-2y^2}{\sqrt{(t^2 - y^2)^3}} \left(I_1 \left(\sqrt{t^2 - y^2} \right) + J_1 \left(\sqrt{t^2 - y^2} \right) \right) \\
&\quad + \frac{t^2}{t^2 - y^2} \left(I_0 \left(\sqrt{t^2 - y^2} \right) + I_2 \left(\sqrt{t^2 - y^2} \right) + J_0 \left(\sqrt{t^2 - y^2} \right) - J_2 \left(\sqrt{t^2 - y^2} \right) \right) \\
&\quad - I_0 \left(\sqrt{t^2 - y^2} \right) - J_0 \left(\sqrt{t^2 - y^2} \right); \\
u_4^2 &= 2 \left(\frac{\partial u_2^3}{\partial t} - u_0^2 \right) = \frac{-2y^2}{\sqrt{(t^2 - y^2)^3}} \left(I_1 \left(\sqrt{t^2 - y^2} \right) - J_1 \left(\sqrt{t^2 - y^2} \right) \right) \\
&\quad + \frac{t^2}{t^2 - y^2} \left(I_0 \left(\sqrt{t^2 - y^2} \right) + I_2 \left(\sqrt{t^2 - y^2} \right) - J_0 \left(\sqrt{t^2 - y^2} \right) + J_2 \left(\sqrt{t^2 - y^2} \right) \right) \\
&\quad - I_0 \left(\sqrt{t^2 - y^2} \right) + J_0 \left(\sqrt{t^2 - y^2} \right).
\end{aligned}$$

It is also easy to verify that $u_4^1 = u_4^3 = 0$.

By using the well-known integrals for Bessel functions [3-5], we have

$$\begin{aligned}
\int_{-t}^t u_0^0 dy &= \sinh t + \sin t, \quad \int_{-t}^t u_0^2 dy = \sinh t - \sin t, \quad \int_{-t}^t u_1^1 dy = \int_{-t}^t u_1^3 dy = 0, \\
\int_{-t}^t u_2^1 dy &= 2 \int_{-t}^t \frac{\partial u_0^2}{\partial t} dy = 2 \left(\frac{\partial}{\partial t} \int_{-t}^t u_0^2 dy - u_0^2(t, t) - u_0^2(t, -t) \right) \\
&= 2 \cosh t - 2 \cos t, \\
\int_{-t}^t u_2^3 dy &= 2 \int_{-t}^t \frac{\partial u_0^0}{\partial t} dy = 2 \left(\frac{\partial}{\partial t} \int_{-t}^t u_0^0 dy - u_0^0(t, t) - u_0^0(t, -t) \right) \\
&= 2 \cosh t + 2 \cos t - 4.
\end{aligned}$$

As an example, we obtain the pdf in the case where $m = 1$. In this case, $e_1 = 1$, and, hence, we can consider the functions $\sum_{l=0}^4 u_k^l(t, y)$, $k = 0, 1, 2, \dots$ as solutions of Eq. (5) for $m = 1$.

For $t \leq |y|$, consider the function $g(t, y) = g_c(t, y) + g_s(t, y)$ of the form

$$\begin{aligned} g_c(t, y) &= \frac{1}{2} (u_0^0(t, y) + u_0^2(t, y)) + \frac{1}{4} (u_1^1(t, y) + u_1^3(t, y) + u_2^1(t, y) + u_2^3(t, y)) \\ &= \frac{I_0(\sqrt{t^2 - y^2})}{2} + \frac{t + y}{2\sqrt{t^2 - y^2}} I_1(\sqrt{t^2 - y^2}) \end{aligned}$$

and $g_s(t, y) = \delta(t - y)$.

It is easily seen that the function $g_c(t, y)$ is a solution of the equation for $t < y$:

$$(11) \quad \left(\frac{\partial^2}{\partial t^2} - \frac{\partial^2}{\partial y^2} \right) g(t, y) - g(t, y) = 0.$$

In addition, we have $\lim_{y \uparrow t} g_c(t, y) = \frac{1}{2}(1 + t)$ and $\lim_{y \downarrow -t} g_c(t, y) = \frac{1}{2}$. To avoid cumbersome calculations, we put $v = 1$.

Therefore, $f(t, x) = e^{-t}g(t, x)$ is a solution of the equation

$$(12) \quad \left(\frac{\partial}{\partial t} - \frac{\partial}{\partial x} + 1 \right) \left(\frac{\partial}{\partial t} + \frac{\partial}{\partial x} + 1 \right) f_c(t, x) - f_c(t, x) = 0,$$

$$f_s(t, x) = \delta(t - x)e^{-t}.$$

In addition, $f_c(t, x)$ satisfies the conditions

$$\lim_{x \uparrow t} f_c(t, x) = \frac{1}{2}(e^{-t} + te^{-t}), \quad \lim_{x \downarrow -t} f_c(t, x) = \frac{1}{2}e^{-t}.$$

For all $t > 0$, we have $\int_{-t}^t f(t, x)dx = 1$.

For a small $\varepsilon > 0$, consider the probability $P\{0 < t - x(t) < \varepsilon\}$.

Let us verify that $\lim_{x \uparrow t} f_c(t, x) = \lim_{\varepsilon \downarrow 0} \frac{P\{0 < t - x(t) < \varepsilon\}}{\varepsilon}$, i.e.,

$$\lim_{\varepsilon \downarrow 0} \frac{P\{0 < t - x(t) < \varepsilon\}}{\varepsilon} = \frac{1}{2}(e^{-t} + te^{-t}).$$

Indeed, it is easily seen that

$$\begin{aligned} P\{0 < t - x(t) \leq \varepsilon\} &= P\left\{t - \frac{\varepsilon}{2} \leq \theta_1 < t\right\} + \int_0^t P\left\{\theta_3 \geq t - u, \theta_2 \leq \frac{\varepsilon}{2}, \theta_1 \in du\right\} \\ &\quad + o(\varepsilon), \end{aligned}$$

where θ_i , $i = 1, 2, 3$ are independent exponentially distributed random variables.

The random variable θ_1 is the time of the first velocity alternation, θ_2 is the time interval between the first and second velocity alternations, and θ_3 is the time interval between the second and third velocity alternations.

We have $P\{t - \frac{\varepsilon}{2} \leq \theta_1 < t\} = e^{-t + \frac{\varepsilon}{2}} - e^{-t}$. Moreover, it is easy to calculate

$$\begin{aligned} \int_0^t P\left\{\theta_3 \geq t - u, \theta_2 \leq \frac{\varepsilon}{2}, \theta_1 \in du\right\} &= (1 - e^{-\frac{\varepsilon}{2}}) \int_0^t e^{-t+u} e^{-u} du \\ &= (1 - e^{-\frac{\varepsilon}{2}}) te^{-t}. \end{aligned}$$

Whence, it is easy to verify that $\lim_{\varepsilon \downarrow 0} \frac{P\{0 < t - x(t) < \varepsilon\}}{\varepsilon} = \frac{1}{2}(e^{-t} + te^{-t})$.

Similarly, $P\{t + x(t) \leq \varepsilon\} = P\left\{\theta_2 \geq t - \frac{\varepsilon}{2}, \theta_1 \leq \frac{\varepsilon}{2}\right\} + o(\varepsilon)$. This implies that

$$\lim_{\varepsilon \downarrow 0} \frac{P\{t + x(t) < \varepsilon\}}{\varepsilon} = \frac{1}{2}e^{-t} = \lim_{x \downarrow -t} f_c(t, x).$$

Therefore, $f_c(t, x)$ is a solution of the Goursat problem for the linear second-order hyperbolic equation that ensures the uniqueness of the solution of Eq. (12) with conditions (4). This means that $f(t, x)$ is the pdf of the particle's position for $m = 1$.

It is worth to remark that the function $f(t, x)$ coincides with the result obtained in [5].

We now turn to the case $m = 2$ and continue to calculate the integrals of u_k^l .

It follows from $u_4^0 = 2\frac{\partial u_2^1}{\partial t} - 2u_0^0$ that

$$\begin{aligned} \int_{-t}^t u_4^0 dy &= 2 \left(\frac{\partial}{\partial t} \int_{-t}^t u_2^1 dy - u_2^1(t, t) - u_2^1(t, -t) \right) - 2\sinh t - 2\sin t \\ &= 4(\sinh t + \sin t - t) - 2\sinh t - 2\sin t = 2\sinh t + 2\sin t - 4t. \end{aligned}$$

Next, it follows from $u_4^2 = 2\frac{\partial u_2^3}{\partial t} - 2u_0^2$ that

$$\begin{aligned} \int_{-t}^t u_4^2 dy &= 2 \left(\frac{\partial}{\partial t} \int_{-t}^t u_2^3 dy - u_2^3(t, t) - u_2^3(t, -t) \right) - 2\sinh t + 2\sin t \\ &= 4\sinh t - 4\sin t - 2\sinh t + 2\sin t = 2\sinh t - 2\sin t. \end{aligned}$$

For $t \leq |y|$, we introduce the function $g(t, y) = g_c(t, y) + g_s(t, y)$, where

$$g_c(t, y) = \frac{1}{2}u_0^2(t, y) + \frac{1}{4}(u_1^1(t, y) + u_1^3(t, y) + u_2^1(t, y) + u_2^3(t, y) + u_4^0(t, y)),$$

$$(13) \quad g_s(t, y) = \delta(t - y) + t\delta(t - y).$$

By construction, the function $g_c(t, y)$ is a solution of the equation

$$(14) \quad \left(\frac{\partial^2}{\partial t^2} - \frac{\partial^2}{\partial y^2} \right) g(t, y) - g(t, y) = 0.$$

Therefore, the function $f_c(t, x) = e^{-t}g_c(t, x)$ is a solution of Eq. (1) for $m = 2$ ($\lambda = v = 1$).

We put $f(t, x) = f_c(t, x) + e^{-t}g_s(t, x)$. Taking into account the values of the integrals of functions, which are involved in the expression for $g_c(t, y)$, we have $\int_{-t}^t f(t, x)dx = 1$ for all $t \geq 0$.

Let us prove that $\lim_{x \uparrow t} f_c(t, x) = \lim_{\varepsilon \downarrow 0} \frac{P\{0 < t-x(t) < \varepsilon\}}{\varepsilon}$ and $\lim_{x \downarrow -t} f_c(t, x) = \lim_{\varepsilon \downarrow 0} \frac{P\{t+x(t) < \varepsilon\}}{\varepsilon}$.

It follows from Lemma 2 that, for $m = 2$,

$$\lim_{\varepsilon \downarrow 0} \frac{P\{0 < t-x(t) < \varepsilon\}}{\varepsilon} = \frac{1}{2}te^{-t}$$

and

$$\lim_{\varepsilon \downarrow 0} \frac{P\{t+x(t) < \varepsilon\}}{\varepsilon} = 0.$$

It is easy to verify that $\lim_{y \uparrow t} u_4^0(t, y) = 0$, $\lim_{y \uparrow t} u_0^2(t, y) = 0$, and, consequently,

$$\begin{aligned} \lim_{y \uparrow t} g_c(t, y) &= \lim_{y \uparrow t} \frac{t+y}{2\sqrt{t^2-y^2}} I_1(\sqrt{t^2-y^2}) = \frac{t}{2}, \\ (15) \quad \lim_{y \downarrow -t} g_c(t, y) &= \lim_{y \downarrow -t} \frac{t+y}{2\sqrt{t^2-y^2}} I_1(\sqrt{t^2-y^2}) = 0. \end{aligned}$$

Thus,

$$\begin{aligned} \lim_{x \uparrow t} f_c(t, x) &= \frac{1}{2}te^{-t} = \lim_{\varepsilon \downarrow 0} \frac{P\{t-x(t) < \varepsilon\}}{\varepsilon}, \\ (16) \quad \lim_{x \downarrow -t} f_c(t, x) &= 0 = \lim_{\varepsilon \downarrow 0} \frac{P\{t+x(t) < \varepsilon\}}{\varepsilon}. \end{aligned}$$

Let us show that conditions (15) with the condition $\int_{-t}^t g(t, y) e^{-t} dx = 1$ insure the uniqueness of the solution $g_c(t, y)$ for Eq. (14) and consequently, the uniqueness of the solution $f_c(t, x)$ of Eq. (12).

It is easily seen that each solution of Eq. (11) is a solution of Eq. (14). By changing the variables $s = t + y$, $p = t - y$, we reduce Eq. (14) to

$$(17) \quad \frac{\partial^4}{\partial s^2 \partial p^2} G(s, p) - G(s, p) = 0.$$

Passing to the Fourier transform $\hat{G}(s, \alpha) = \int_0^\infty G(s, p) e^{i\alpha p} dp$ in Eq. (17), we get the ordinary differential equation of order 4. Taking into account that $\lim_{y \downarrow -t} g_c(t, y) = 0$, we have

$$(18) \quad \hat{G}(0, \alpha) = 0.$$

Hence, at most four independent solutions of the ordinary differential equation satisfy the initial condition (18) for each α . Passing to the inverse Fourier transform, we have four independent solutions of Eq. (14) under the condition $\lim_{x \downarrow -t} g_c(t, x) = 0$, and just two of them satisfy Eq. (14) but not Eq. (11). By construction, one of these solutions, $g_c(t, y)$, is given by Eq. (13). As another solution, we can take

$$g_2(t, y) = u_0^2(t, y) + u_4^0(t, y).$$

It is easy to verify that no linear combination $c(t, y)$ of the functions $g_c(t, y)$ and $g_2(t, x)$ satisfies conditions (16) and $\int_{-t}^t (c(t, x) + g_s(t, y)) e^{-t} dx = 1$ for all $t > 0$, but solution $g_c(t, y)$.

Therefore, the function $f(t, x)$ is the pdf of the particle position at time t for $m = 2$, $v = \lambda = 1$, and has the form

$$\begin{aligned} f(t, x) = & -\frac{J_0(\sqrt{t^2 - x^2})}{2} e^{-t} + \frac{(t+x)e^{-t}}{2\sqrt{t^2 - x^2}} I_1(\sqrt{t^2 - x^2}) \\ & - \frac{x^2 e^{-t}}{2\sqrt{(t^2 - x^2)^3}} \left(I_1(\sqrt{t^2 - x^2}) + J_1(\sqrt{t^2 - x^2}) \right) \\ & + \frac{t^2 e^{-t}}{4(t^2 - x^2)} \left(I_0(\sqrt{t^2 - x^2}) + I_2(\sqrt{t^2 - x^2}) + J_0(\sqrt{t^2 - x^2}) - J_2(\sqrt{t^2 - x^2}) \right) \\ & + \delta(t-x) e^{-t} + t\delta(t-x) e^{-t}. \end{aligned}$$

In the same way as the pdf $f(t, x)$ of the particle position for $m = 2$ was obtained, we can also get solutions of Eq. (1) with conditions (2) and (4) for each $m > 2$.

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